

Global Constraints in Software Testing Applications

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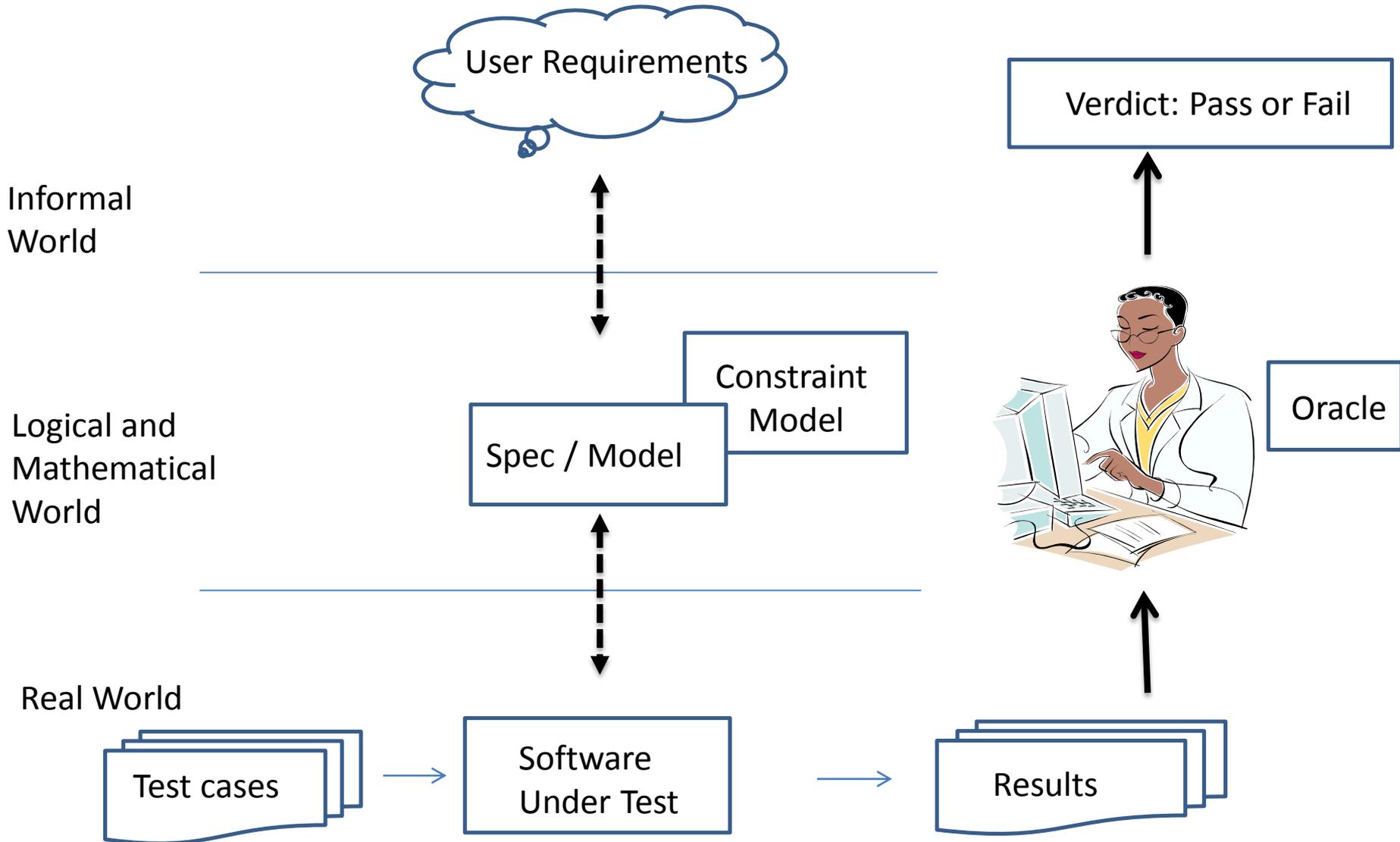
[**simula** . research laboratory]
- by thinking constantly about it



Agenda

- I. Software Testing
- II. Optimal Test Suite Reduction
- III. Automatic Test Case Generation
- IV. Conclusions and Perspectives

Software Testing



// Software Testing

Software test preparation is a **cognitively complex task**:

- Requires to understand both model and code to create interesting test cases ;
- Program's input space is usually very large (sometimes unbounded) ;
- Complex software (e.g., implementing ODEs or PDEs) yields to complex bugs ;
- Test oracles are hard to define (non-testable programs) ;

Not easily amenable to automation:

- Automatic test data generation is undecidable in the general case!
- Exploring the input space yields to combinatorial explosion ;
- Fully automated oracles are usually not available ;

// How software testing differs from other program verification techniques?

☞ **Static analysis** finds simple faults (division-by-zero, overflows, ...) at compile-time, while **software testing** finds functional faults at run-time (P returns 3 while 2 was expected)

☞ **Program proving** aims at formally proving mathematical invariants, while **software testing** evaluates the program in its execution environment

☞ **Model-checking** explores paths of a model of the software under test for checking temporal properties or finding counter-examples, while **software testing** is based on program executions

Some Hot Research Topics in Software Testing

- ❑ Automatic test case generation

Find test cases to exercise specific behaviors, to execute specific code locations, to cover some test objectives (e.g., all-statements, all-k-paths)

- ❑ Test suite reduction, test suite prioritization, test execution scheduling

- ❑ Robustness and performance testing

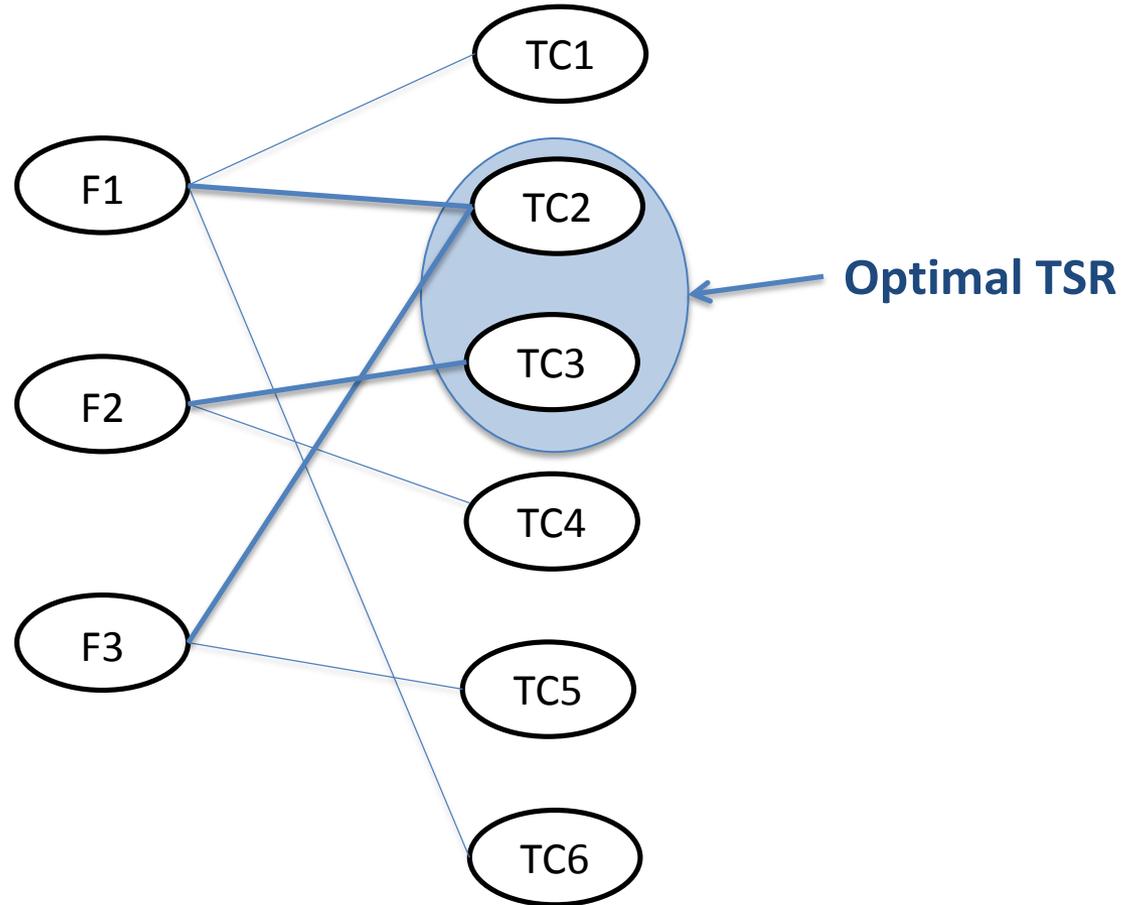
- ❑ Testing complex code (e.g., floating-point and iterative computations)

Our thesis: **Global constraints** can efficiently tackle these problems!

(High-level primitives with specialised filtering algorithms)

Optimal Test Suite Reduction

Optimal TSR: the core problem



Optimal TSR: find a minimal subset of TC such that each F is covered at least once (Practical importance but NP-hard problem!) – An instance of *Minimum Set Cover*

The nvalue global constraint

$$\mathit{nvalue}(n, v)$$

Where:

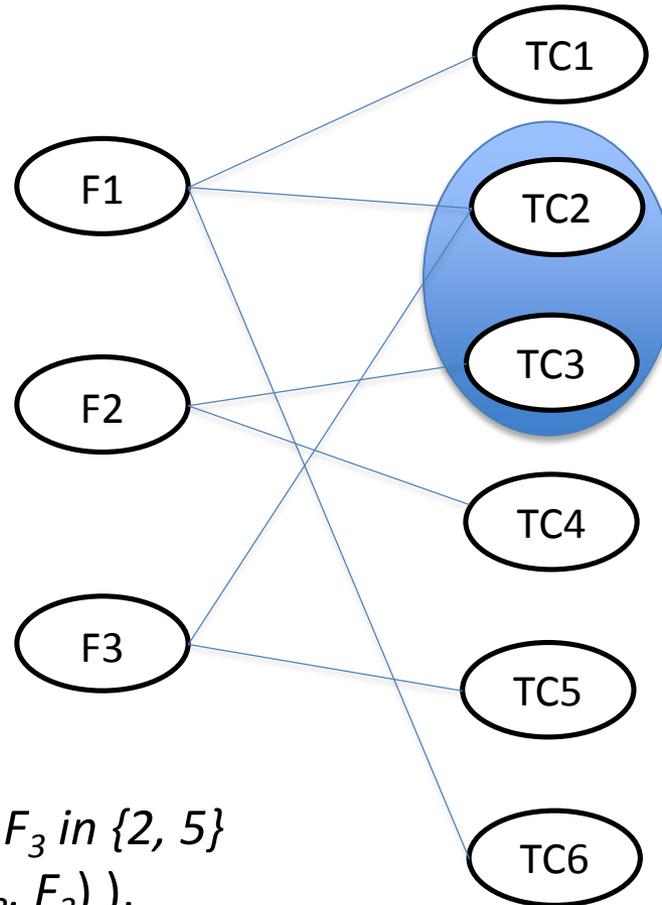
n is an FD_variable

$v = (v_1, \dots, v_k)$ is a vector of FD_variables

$$\mathit{nvalue}(n, v) \text{ holds iff } n = \mathit{card}(\{v_i\}_{i \text{ in } 1..k})$$

Introduced in [Pachet and Roy'99], first filtering algorithm in [Beldiceanu'01]
Solution existence for nvalue is NP-hard [Bessiere et al. '04]

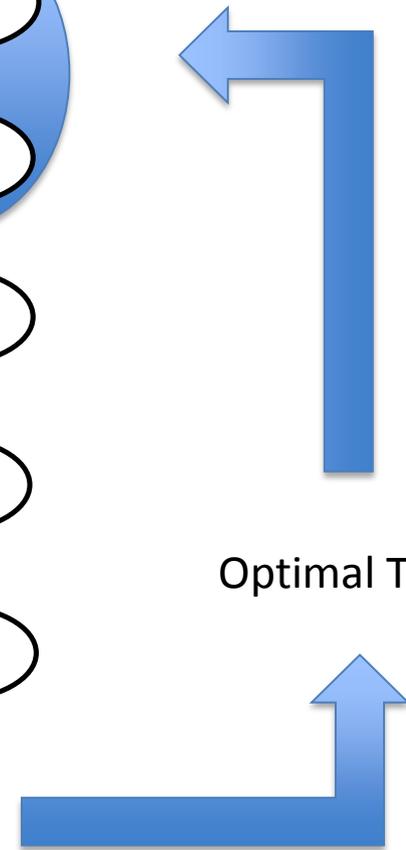
Optimal TSR: CP model with nvalue (1)



F_1 in {1, 2, 6}, F_2 in {3, 4}, F_3 in {2, 5}
nvalue(MaxNvalue, (F₁, F₂, F₃)),
label(minimize(MaxNvalue))

/* branch-and-bound search among feasible solutions */

Optimal TSR



The global_cardinality constraint

$$gcc(t, d, v)$$

Where

$t = (t_1, \dots, t_N)$ is a vector of N variables, each t_j in $Min_j..Max_j$

$d = (d_1, \dots, d_k)$ is a vector of k values

$v = (v_1, \dots, v_k)$ is a vector of k variables, each v_i in $Min_i..Max_i$

$$gcc(t, d, v) \text{ holds iff } \forall i \text{ in } 1..k, \\ v_i = \text{card}(\{t_j = d_i\}_{j \text{ in } 1..N})$$

Filtering algorithms for gcc are based on max flow computations in a network flow [Regin AAAI'96]

Example

$\text{gcc}((F_1, F_2, F_3), (1, 2, 3, 4, 5, 6), (V_1, V_2, V_3, V_4, V_5, V_6))$

means that:

In a solution of TSR

TC_1 covers exactly V_1 requirements in (F_1, F_2, F_3)

TC_2 " V_2 "

TC_3 " V_3 "

...

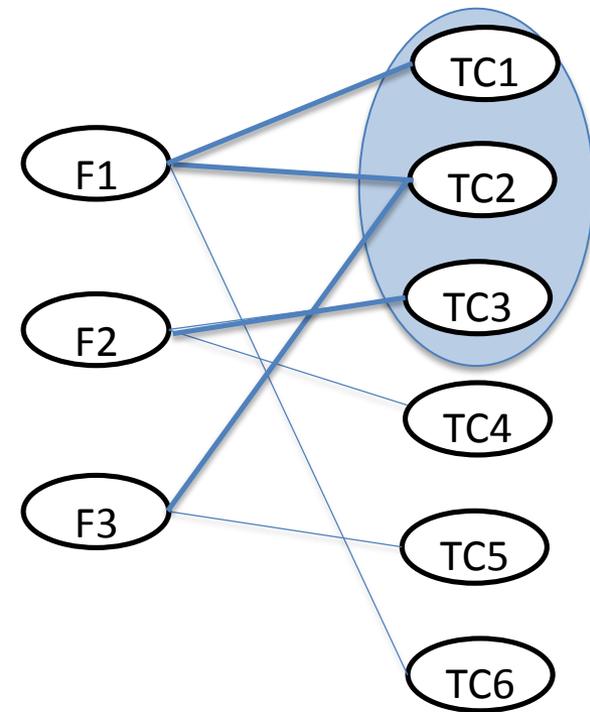
Where $F_1, F_2, F_3, V_1, V_2, V_3, \dots$ denote finite-domain variables

F_1 in $\{1, 2, 6\}$, F_2 in $\{3, 4\}$, F_3 in $\{2, 5\}$

V_1 in $\{0, 1\}$, V_2 in $\{0, 2\}$, V_3 in $\{0, 1\}$, V_4 in $\{0, 1\}$, V_5 in $\{0, 1\}$, V_6 in $\{0, 1\}$

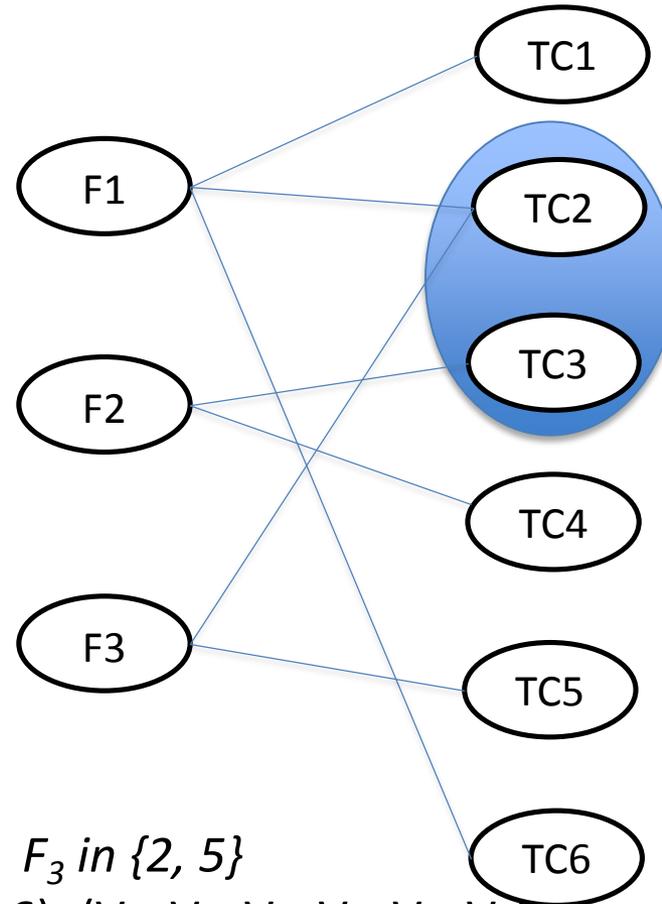
Here, for example, $V_1 = 1, V_2 = 2, V_3 = 1, V_4 = 0, V_5 = 0, V_6 = 0$ is a feasible solution

But, not an optimal one!



Optimal TSR: CP model with two gcc (2)

[Gotlieb Marijan ISSTA'2014]



F_1 in $\{1, 2, 6\}$, F_2 in $\{3, 4\}$, F_3 in $\{2, 5\}$
gcc((F₁, F₂, F₃), (1,2,3,4,5,6), (V₁, V₂, V₃, V₄, V₅, V₆)),
gcc((V₁, V₂, V₃, V₄, V₅, V₆), (0-_), (Max0Req-_)),
label(maximize(Max0Req))

Optimal TSR

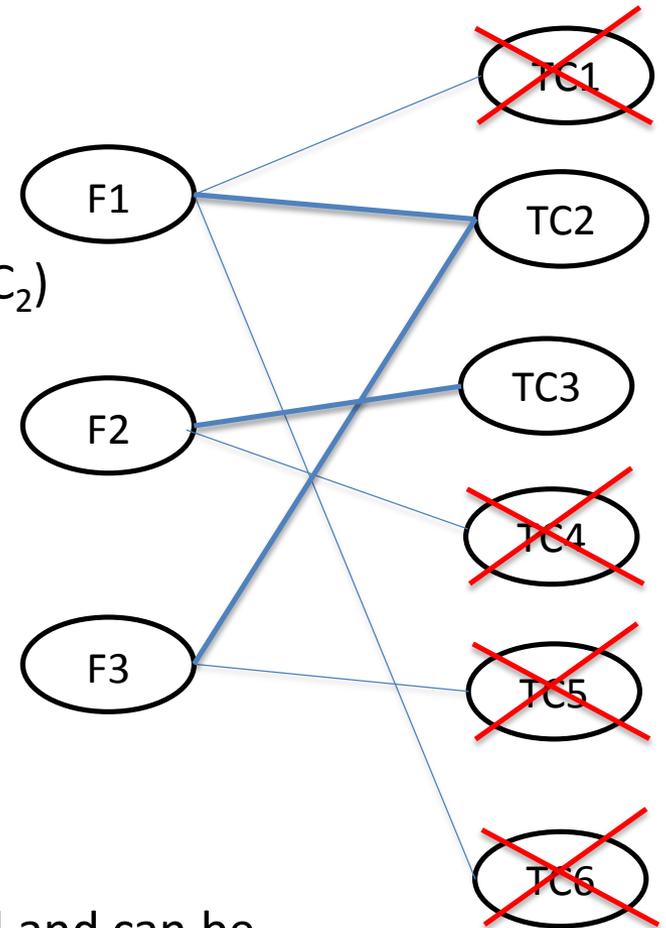
/* search heuristics by enumerating the Vi first */

Introducing model pre-treatment

F_1 in $\{1, 2, 6\} \rightarrow F_1 = 2$ as $\text{cov}(TC_1) = \text{cov}(TC_6) \subset \text{cov}(TC_2)$
withdraw TC_1 and TC_6

F_3 is covered \rightarrow withdraw TC_5

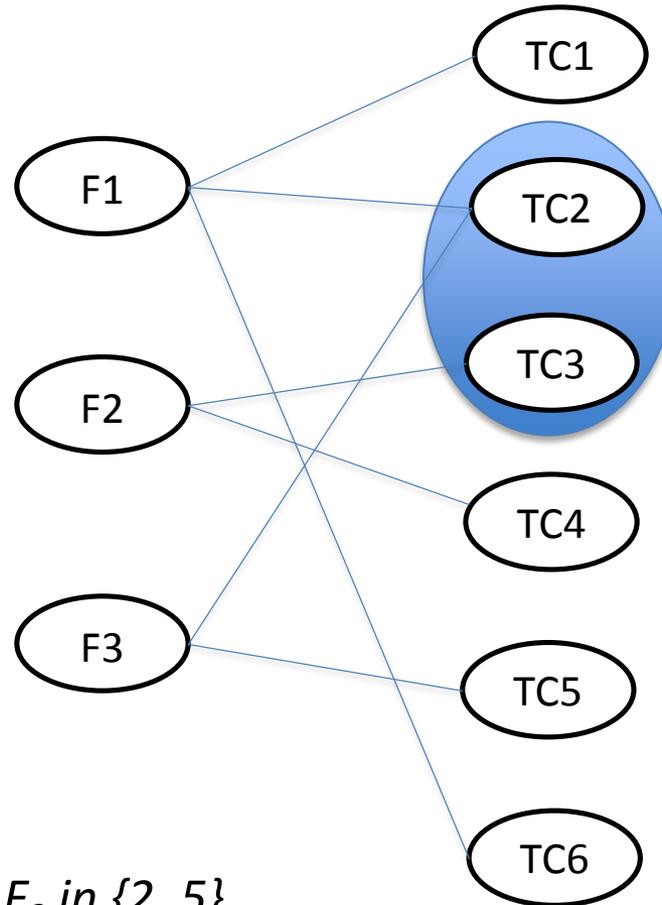
F_2 in $\{3,4\} \rightarrow$ e.g., $F_2 = 3$, withdraw TC_4



Three such pre-treatment rules have been identified and can be included to simplify the problem

But, they are currently statically applied!

3. Optimal TSR: CP model Mixt (3)



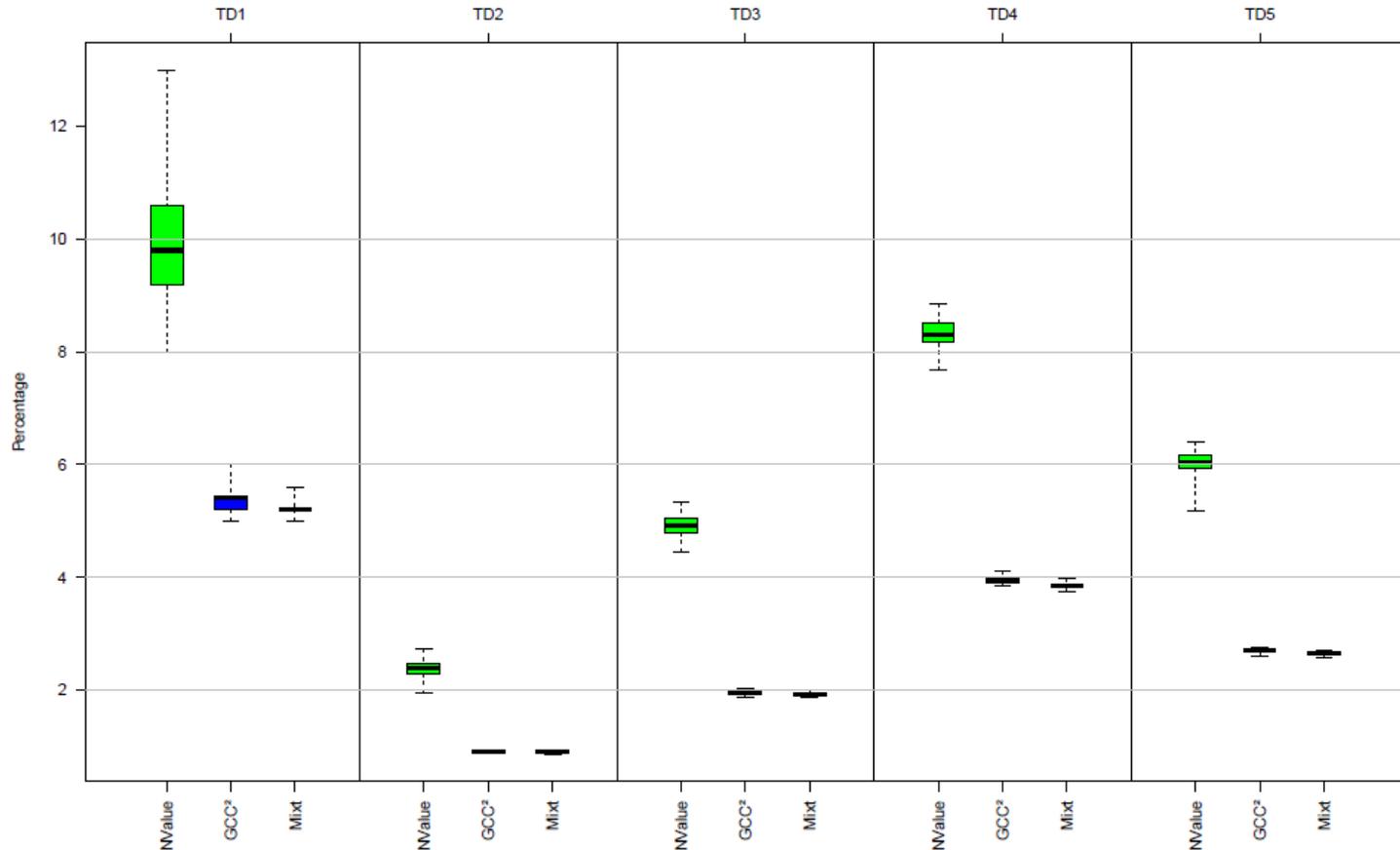
Optimal TSR



F_1 in $\{1, 2, 6\}$, F_2 in $\{3, 4\}$, F_3 in $\{2, 5\}$
gcc((F₁, F₂, F₃), (1,2,3,4,5,6), (V₁, V₂, V₃, V₄, V₅, V₆)),
nvalue(MaxNvalue, (V₁, V₂, V₃, V₄, V₅, V₆)),
label(minimize(MaxNvalue))

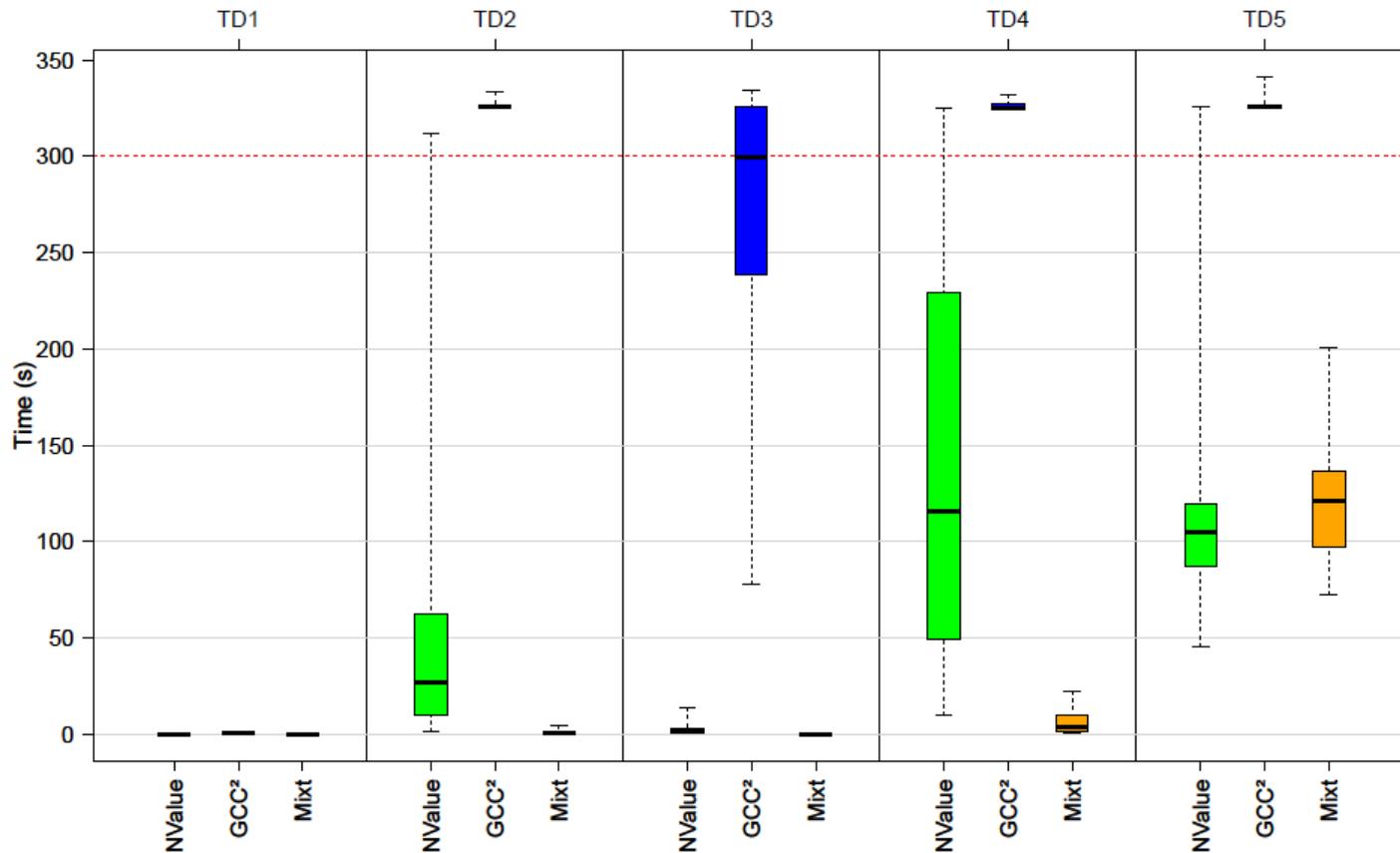
/* + pre-treatment + labelling heuristics based on max */

Model comparison on random instances (Reduced Test Suite percentage in 30sec of search)



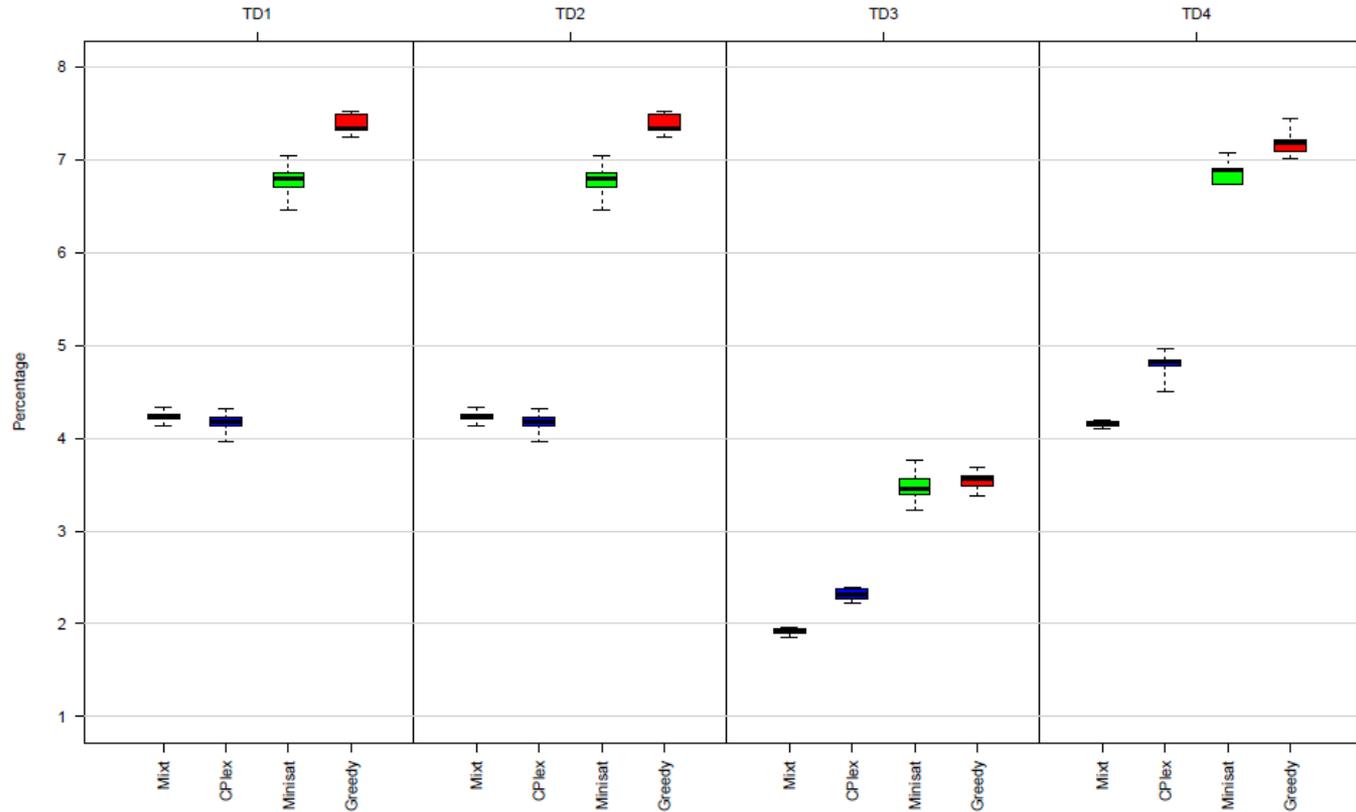
| | TD1 | TD2 | TD3 | TD4 | TD5 |
|--------------|-----|------|------|------|------|
| Requirements | 250 | 500 | 1000 | 1000 | 1000 |
| Test cases | 500 | 5000 | 5000 | 5000 | 7000 |
| Density | 20 | 20 | 20 | 8 | 8 |

Model comparison on random instances (CPU time to find a global optimum)



| | TD1 | TD2 | TD3 | TD4 | TD5 |
|--------------|-----|-----|-----|-----|-----|
| Requirements | 20 | 90 | 60 | 60 | 30 |
| Test cases | 70 | 100 | 100 | 200 | 500 |
| Density | 8 | 20 | 20 | 20 | 8 |

Comparison with other approaches (Reduced Test Suite percentage in 60 sec)



| | TD1 | TD2 | TD3 | TD4 |
|--------------|------|------|------|------|
| Requirements | 1000 | 1000 | 1000 | 2000 |
| Test cases | 5000 | 5000 | 5000 | 5000 |
| Density | 7 | 7 | 20 | 20 |

Automatic Test Case Generation

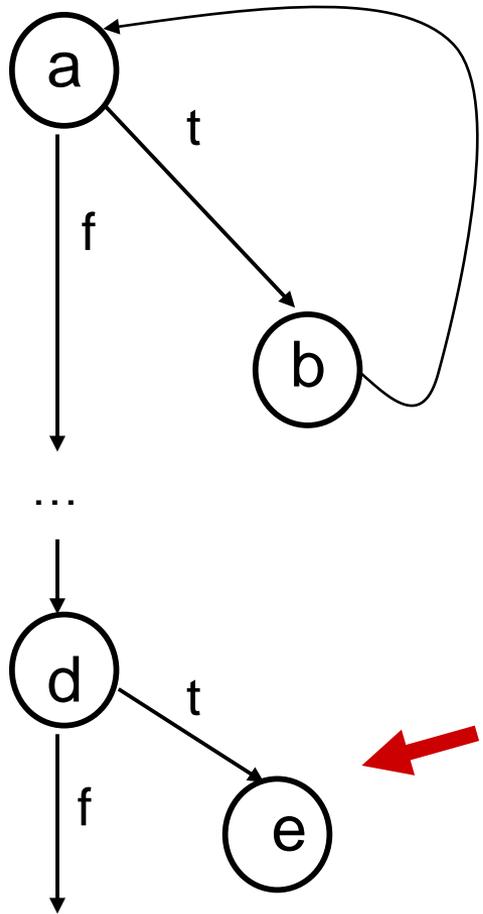
An example problem

```
f( int i, ... )  
{  
a.   j = 100;  
   while( i > 1)  
b.     { j++ ; i-- ; }  
  
   ...  
d.   if( j > 500)  
e.     ...
```



value of i to reach e ?

Undecidable problem!



Path-oriented exploration

```
f( int i, ... )  
{
```

```
a.   j = 100;  
    while( i > 1)  
b.   { j++ ; i-- ;
```

...

```
d.   if( j > 500)
```

```
e.   ...
```

1. Path selection

e.g., (a-b)¹⁴-...-d-e

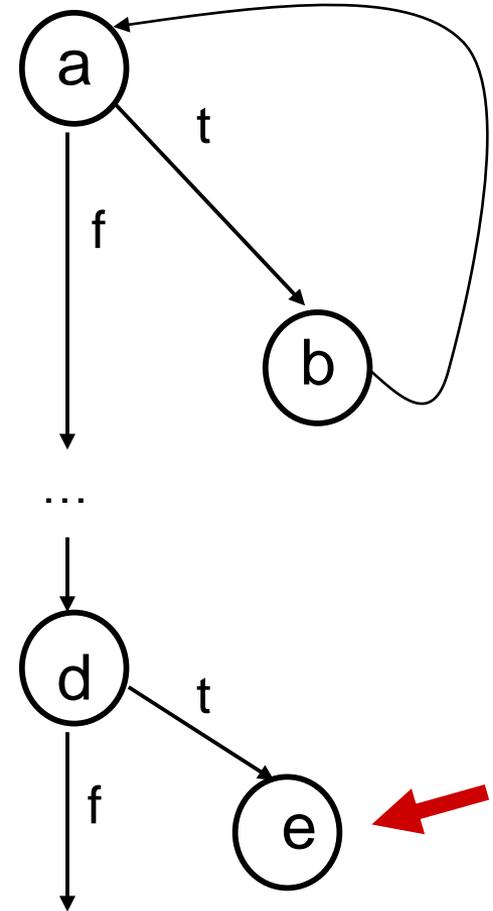
2. Path condition generation (via symbolic exec.)

$j_1=100, i_1>1, j_2=j_1+1, i_2=i_1-1, i_2>1, \dots, j_{15}>500$

3. Path condition solving

unsatisfiable \rightarrow FAIL

Backtrack !



Constraint-based program exploration

(Gotlieb et al. ISSTA'98)

```
f( int i, ... )  
{  
a.   j = 100;  
    while( i > 1)  
b.   { j++ ; i-- ;}  
    ...  
d.   if( j > 500)  
e.   ...
```

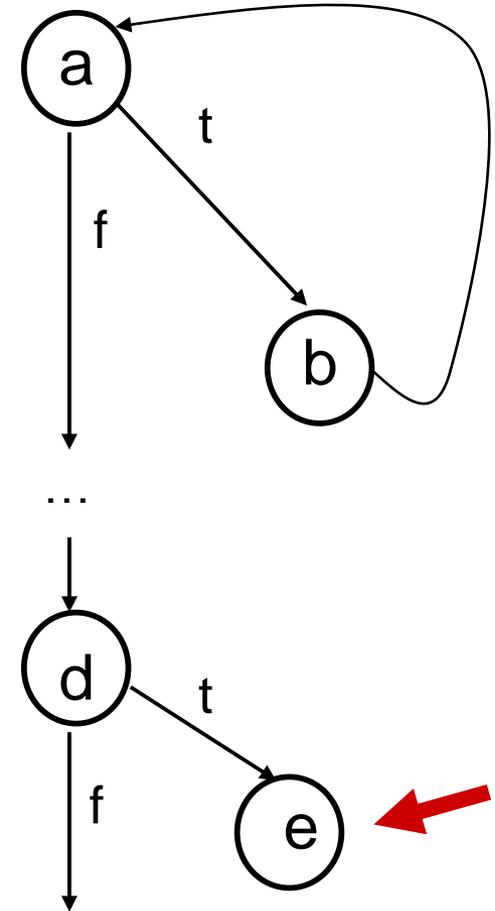
1. Program (under Static Single Assignment form) as constraints

2. Control dependencies generation;

$j_1=100, i_3 \leq 1, j_3 > 500$

3. Global constraint reasoning

$j_1 \neq j_3$ entailed \rightarrow unroll the loop 400 times $\rightarrow i_1$ in $401 \dots 2^{31}-1$

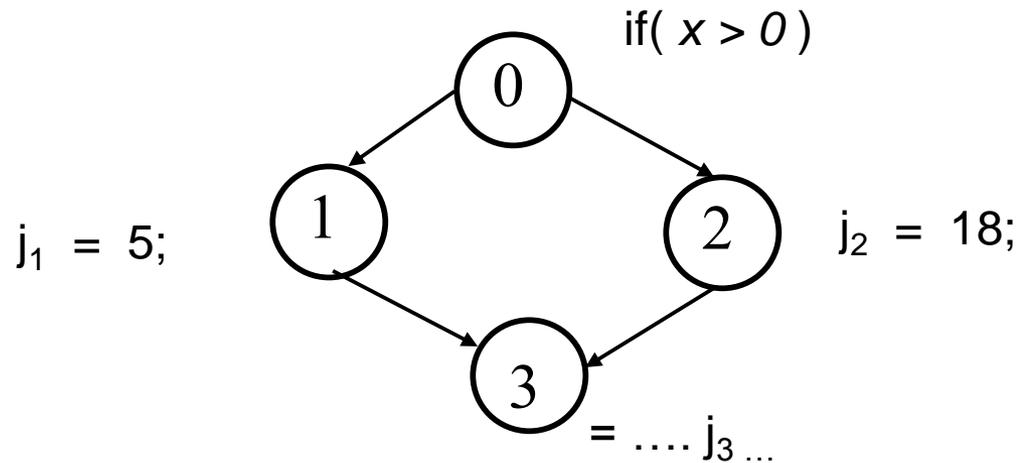


No backtrack !

Program as constraints

- ✓ Type declaration: `signed long x;` \rightarrow $x \text{ in } -2^{31}..2^{31}-1$
- ✓ Assignments: `i*=++i;` \rightarrow $i_2 = (i_1+1)^2$
- ✓ Memory and array accesses and updates (*Charretier et al. JSS'09, Bardin et al. CPAIOR'12*):
`v=A[i]` (or `p=Mem[&p]`) \rightarrow variations of element/3
- ✓ Control structures: dedicated global constraints
 - Conditionnals (SSA) `if D then C1; else C2` \rightarrow ite/6
 - Loops (SSA) `while D do C` \rightarrow w/5

Conditional as a global constraint: ite/6

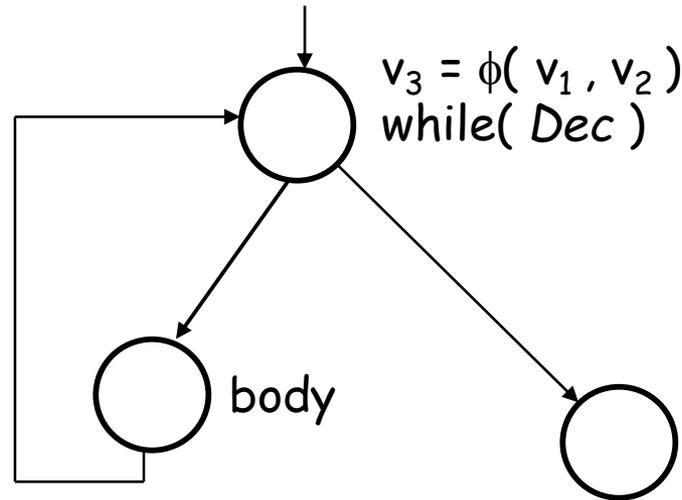


$\text{ite}(x > 0, j_1, j_2, j_3, j_1 = 5, j_2 = 18)$ iff

- ♦ $x > 0 \rightarrow j_1 = 5 \wedge j_3 = j_1$
- ♦ $\neg(x > 0) \rightarrow j_2 = 18 \wedge j_3 = j_2$
- ♦ $\neg(x > 0 \wedge j_1 = 5 \wedge j_3 = j_1) \rightarrow \neg(x > 0) \wedge j_2 = 18 \wedge j_3 = j_2$
- ♦ $\neg(\neg(x > 0) \wedge j_3 = j_2) \rightarrow x > 0 \wedge j_1 = 5 \wedge j_3 = j_1$
- ♦ $\text{Join}(x > 0 \wedge j_1 = 5 \wedge j_3 = j_1, \neg(x > 0) \wedge j_2 = 18 \wedge j_3 = j_2)$

Implemented as a global constraint: interface, awakening conditions, filtering algo.

While loop as a global constraint: w/5



$w(\text{Dec}, V_1, V_2, V_3, \text{body})$ iff

- ◆ $\text{Dec}_{V_3 \leftarrow V_1} \rightarrow \text{body}_{V_3 \leftarrow V_1} \wedge w(\text{Dec}, v_2, v_{\text{new}}, v_3, \text{body}_{V_2 \leftarrow V_{\text{new}}})$
- ◆ $\neg \text{Dec}_{V_3 \leftarrow V_1} \rightarrow v_3 = v_1$
- ◆ $\neg(\text{Dec}_{V_3 \leftarrow V_1} \wedge \text{body}_{V_3 \leftarrow V_1}) \rightarrow \neg \text{Dec}_{V_3 \leftarrow V_1} \wedge v_3 = v_1$
- ◆ $\neg(\neg \text{Dec}_{V_3 \leftarrow V_1} \wedge v_3 = v_1) \rightarrow \text{Dec}_{V_3 \leftarrow V_1} \wedge \text{body}_{V_3 \leftarrow V_1} \wedge w(\text{Dec}, v_2, v_{\text{new}}, v_3, \text{body}_{V_2 \leftarrow V_{\text{new}}})$
- ◆ $\text{join}(\text{Dec}_{V_3 \leftarrow V_1} \wedge \text{body}_{V_3 \leftarrow V_1} \wedge w(\text{Dec}, v_2, v_{\text{new}}, v_3, \text{body}_{V_2 \leftarrow V_{\text{new}}}), \neg \text{Dec}_{V_3 \leftarrow V_1} \wedge v_3 = v_1)$

```
f( int i ) {
  j = 100;
  while( i > 1)
    { j++ ; i-- ;}
  ...
  if( j > 500)
    ...
}
```

w(Dec, V₁, V₂, V₃, body) :-

- ◆ Dec_{V₃←V₁} → body_{V₃←V₁} ∧ w(Dec, v₂, v_{new}, v₃, body_{V₂←V_{new}})
- ◆ ¬Dec_{V₃←V₁} → v₃=v₁
- ◆ ¬(Dec_{V₃←V₁} ∧ body_{V₃←V₁}) → ¬Dec_{V₃←V₁} ∧ v₃=v₁
- ◆ ¬(¬Dec_{V₃←V₁} ∧ v₃=v₁) →
Dec_{V₃←V₁} ∧ body_{V₃←V₁} ∧ w(Dec, v₂, v_{new}, v₃, body_{V₂←V_{new}})
- ◆ join(Dec_{V₃←V₁} ∧ body_{V₃←V₁} ∧ w(Dec, v₂, v_{new}, v₃, body_{V₂←V_{new}},
¬Dec_{V₃←V₁} ∧ v₃=v₁)

i = 23, j₁ = 100 ?

no

i in 401..2³¹-1

w(i₃ > 1, (i, j₁), (i₂, j₂), (i₃, j₃), j₂ = j₃ + 1 ∧ i₂ = i₃ - 1)

i₃ = 1, j₃ = 122

i₃ = 10 ?

j₁ = 100,
j₃ > 500 ?

Features of the w/5 relation

- ✓ It can be imbricated with other relations (e.g., nested loops $w(\text{cond}_1, v_1, v_2, v_3, w(\text{cond}_2, \dots))$) – It handles unbounded loops
- ✓ Managed by the solver as any other constraint (its consistency is iteratively checked, awakening conditions, success/failure/suspension)
- ✓ By construction, w is unfolded only when necessary but **w may NOT terminate ! (only a semi-correct procedure)**
- ✓ Join is implemented using Abstract Interpretation operators (interval union, Q-polyhedra weak-join operator, simple widening operators)

(Gotlieb et al. CL'2000, Denmat et al. CP'2006)

EUCLIDE: Automatic Test Case Generation for C Programs

[Gotlieb ICST'09, KER'12]

The image shows the Euclide IDE interface. On the left, the C source code for the function `P_rad_eta()` is displayed. The code includes several conditional branches and assignments. In the center, a control flow graph (CFG) visualizes the execution paths of the code, with nodes representing different types of code elements as defined in the legend. On the right, the 'Automatic Test Data Generation' window is open, showing the generated test data for the selected function.

```
void P_rad_eta()
{
    MEM_PBMORDR = PBMORDR;
    PBMORDR = 0x0;
    FM_PBMORDR = 0x0;

    if (!MSTRDR)
    {
        TPMSTRDR = 94;
        TPCODRDR = 194;
        TPIEMRDR = 1875;
        MERDR = 0;
    }
    else
    {
        if (TPCODRDR != 194)
        {
            if (TPCODRDR <= 0)
            {
                trait2_eta();
            }
            else
            {
                if (TPCODRDR <= (194 - 13))
                {
                    if (!DIALRDR)
                    {
                        trait3_eta();
                    }
                    else
                    {
                        local_merdr3g = TP_RDR_7R.merdr3g;
                        if ((local_merdr3g & 0x0001)==0x0001)
                        {
                            trait1_eta();
                        }
                    }
                }
            }
        }
    }
}
```

Legend:

- I/O Node: White circle
- Decision Node: Blue circle
- Code Node: Grey circle
- Goto/Label Node: Red circle
- Cte/Brk Node: Green circle
- Return Node: Dark green circle

Automatic Test Data Generation

| Components | Test Data |
|--|---------------------------|
| File: C:/Users/gotlieb/gotlieb/RECHERCHE/EUCLIDE_V0/examples/ardeta03.cpp | TPCODRDR = 91 |
| Subroutine: P_rad_eta | merdr3g*TP_RDR_7R = 65534 |
| Target node: 21 | local_merdr3g = 32767 |
| Formal parameters: [] | merdr0g*TP_RDR_7R = 32767 |
| Global used: [id(TPCODRDR,514),type(unsigned_short_int,2)],r(no)), .point([id(merdr3g,79),type(unsigned_short_int,2)],r(no)),id(TP_RDR_7R,507),type(unsigned_short_int,2)],r(no)) | local_merdr0g = 32767 |
| | TPIEMRDR = 0 |
| | MEM_PBMORDR = 32767 |
| | DIALRDR = 32768 |
| | PBMORDR = 0 |
| | MSTRDR = 32768 |
| | TPMSTRDR = 0 |
| | MERDR = 32767 |

Symmetric program

Conclusions

- Global constraints (existing ones or user-defined) can efficiently and effectively tackle difficult software testing problems – experimental results and industrial case studies
- So far, only a few subset of existing global constraints have been explored for that purpose (e.g., nvalue, gcc, element, all_different,...)
- Some software testing problems require the creation of dedicated global constraints to facilitate disjunctive reasoning, case-based reasoning or probabilistic reasoning

→ there is room for research in that area!

Perspectives

- More industrial case studies for demonstrating the potential of global constraints for software testing applications
- Using **GCC WITH COSTS** to deal with bi-objective optimisation in test suite reduction (e.g., to also select test cases based on execution time in addition to requirement coverage)
- Test Case Execution Scheduling with **CUMULATIVE**

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